

Jorge Alvarez Tello, Mireya Zapata, & Dennys Paillacho. (2019). Kinematic optimization of a robot head movements for the evaluation of human-robot interaction in social robotics. In *10th International Conference on Applied Human Factors and Ergonomics and the Affiliated Conferences (AHFE 2019)*, Washington D.C.; United States. *Advances in Intelligent Systems and Computing* (Vol. 975, pp. 108–118).